AMENDMENTS TO THE CLAIMS:

Please cancel Claims 1-12.

13. (Original) A method of assembling an actuator assembly of a disk drive, said method comprising the steps of:

providing an actuator arm having a proximal end and a distal end;

providing a suspension arm having a proximal end and a distal end;

fixing a swage plate to the proximal end of the suspension arm, said swage plate including a swage boss extending therefrom;

depositing a film lubricant upon at least an outer surface of said swage boss; and

attaching the suspension arm to the actuator arm by swaging the swage boss to an opening formed in the distal end of the actuator arm.

14. (Original) A method, as claimed in Claim 13, further including the step of:

depositing a film lubricant on the opening in said distal end of the actuator arm prior to said attaching step.

15. (Original) A method, as claimed in Claim 13, wherein:

said film is deposited upon the swage boss by immersing the swage boss in a dilute solution containing the film lubricant, and then draining the solution at a selected rate or raising the swage boss out of the coating solution at a desired rate.

16. (Original) A method, as claimed in Claim 13, wherein said film lubricant is deposited upon the swage boss by spraying.

17. (Original) A method, as claimed in Claim 13, wherein said film lubricant is deposited upon the swage boss by vacuum deposition.

18. (Original) A method, as claimed in Claim 13, wherein said film lubricant is a polymer film.

19. (Original) A method, as claimed in Claim 13, wherein said film lubricant is a solid film.

20. (Original) A method, as claimed in Claim 18, wherein said polymer comprises fluorocarbon.

21. (Original) A method, as claimed in Claim 19, wherein said solid film comprises fluorocarbon.

Please amend Claim 22 as follows:

22. (Presently Amended) A method of reducing torque out retention values between an actuator arm and a suspension arm of a disk drive which are connected by swaging, said method comprising the steps of:

providing swage contact surfaces including an outer surface of a swage boss~~, and an inner surface defining an opening in a distal end of the actuator arm~~; and

applying a lubricant film coating to ~~at least one of~~ said outer surface ~~and said inner surface prior to swaging of the actuator arm and suspension arm~~, thus providing lubrication in a subsequent de-swaging process.

23. (Original) A method, as claimed in Claim 22, wherein:

said lubricant film coating is applied to said swage contact surfaces by immersing said swage contact surfaces in a dilute solution containing the lubricant film coating, and then draining the solution or raising the swage contact surfaces out of the lubricant film coating solution at a selected rate.

24. (Original) A method, as claimed in Claim 22, wherein said lubricant film coating is applied to said swage contact surfaces by spraying.

25. (Original) A method, as claimed in Claim 22, wherein said lubricant film coating is applied to said swage contact surfaces by a vacuum deposition process.

26. (Original) A method, as claimed in Claim 22, wherein said film lubricant is a polymer film.

27. (Original) A method, as claimed in Claim 22, wherein said film lubricant is a solid film.

28. (Original) A method, as claimed in Claim 26, wherein said polymer film comprises fluorocarbon.

29. (Original) A method, as claimed in Claim 27, wherein said solid film comprises fluorocarbon.

Please cancel Claim 30.

Please add the following new claim:

31. (New) A method, as claimed in Claim 22, further comprising the steps of:

providing an inner surface defining an opening in a distal end of the actuator arm; and

applying a lubricant film coating to said inner surface thus providing lubrication in the subsequent de-swaging process.